

Parallel Communicating Automata Systems

by

M. Sakthi Balan

Data Processing Lab

Department of Computer Science

University of Western Ontario

Contents

- Grammar Systems

Contents

- Grammar Systems
- Parallel Communicating Grammar Systems

Contents

- Grammar Systems
- Parallel Communicating Grammar Systems
- Parallel Communicating Automata Systems

Contents

- ❑ Grammar Systems
- ❑ Parallel Communicating Grammar Systems
- ❑ Parallel Communicating Automata Systems
- ❑ Parallel Communicating Finite State Automata

Contents

- ❑ Grammar Systems
- ❑ Parallel Communicating Grammar Systems
- ❑ Parallel Communicating Automata Systems
- ❑ Parallel Communicating Finite State Automata
- ❑ Parallel Communicating Pushdown Automata

Contents

- ❑ Grammar Systems
- ❑ Parallel Communicating Grammar Systems
- ❑ Parallel Communicating Automata Systems
- ❑ Parallel Communicating Finite State Automata
- ❑ Parallel Communicating Pushdown Automata
- ❑ Conclusion

- ❑ System consisting of finite number of grammars working together under a specified protocol to generate languages.
- ❑ Cooperating Distributed (CD) Grammar Systems.
 - Black-board Model.
 - At any time only one component is active.
 - Modes of derivations: t -mode, $*$ -mode, $= k$ -mode, $\leq k$ mode and $\geq k$ -mode.
- ❑ Parallel Communicating (PC) Grammar Systems.
 - Classroom Model.
 - All components work in parallel.
 - Different variants: $\{centralized, non - centralized\} \times \{returning, non - returning\}$.

- ❑ Many FSA working together.
- ❑ Communication by states.
- ❑ The querying component imparts a query symbol in its state information specific to the component to be queried and gets the state of the queried component after communication gets over.

- ❑ Finite number of PDA working together.
- ❑ Communication by stack
- ❑ The querying component imparts a query symbol in its stack specific to the component to be queried and gets the stack information of the queried component in its stack after communication gets over.
- ❑ There should not be any cyclic querying.

- ❑ Centralized: Only one component can query
- ❑ Non-centralized: Any component can query
- ❑ Returning: Once the communication takes place the queried component loses all the stack information and so again starts from its start stack symbol.
- ❑ Non-Returning: The stack of the queried component retains the copy even after the communication.
- ❑ So totally we have four variants
 $\{centralized, non - centralized\} \times \{returning, non - returning\}.$

❑ Cooperating Distributed (CD) $\{FSA, PDA\}$ Systems

→ $CDFSA$ - no increase in power

→ $CDPDA$ - equivalent to Turing machine in all the modes of acceptance

❑ Parallel Communicating (PC) $\{FSA, PDA\}$ Systems

→ $PCFSA$ - equivalent to multi-head finite state automata

→ $PCPDA$ - equivalent to Turing machine in all variants, except one which is still open

A parallel communicating pushdown automata system of degree n is a construct

$$\mathcal{A} = (V, \Delta, A_1, A_2, \dots, A_n, K), n \geq 1$$

where V is the input alphabet, Δ is the alphabet of pushdown symbols, for each $1 \leq i \leq n$, $A_i = (Q_i, V, \Delta, f_i, q_i, Z_i, F_i)$ is a pushdown automaton with the set of states Q_i , the initial state $q_i \in Q_i$, the alphabet of input symbols V , the alphabet of pushdown symbols Δ , the initial pushdown symbols $Z_i \in \Delta$, the set of final states $F_i \subseteq Q_i$, and the transition mapping f_i from $Q_i \times (V \cup \{\epsilon\}) \times \Delta$ into the finite subsets of $Q_i \times \Delta^*$, $K \subseteq \{K_1, K_2, \dots, K_n\} \subseteq \Delta$ is the set of query symbols.

The automata A_1, A_2, \dots, A_n are called the components of the system \mathcal{A} .

If there exists only one i , $1 \leq i \leq n$, such that for A_i , $(r, \alpha) \in f_i(q, a, A)$ with $\alpha \in \Delta^*$, $|\alpha|_K > 0$ for some $r, q \in Q_i$, $a \in V \cup \{\epsilon\}$, $A \in \Delta$, then the system is said to be *centralized* and A_i is said to be the *master* of the system, i.e only one of the component, called the the master, is allowed to introduce queries. For the sake of simplicity, whenever a system is centralized its master is taken to be the first component

We define a configuration of a parallel communicating pushdown automata system as a $3n$ -tuple

$$(s_1, x_1, \alpha_1, s_2, x_2, \alpha_2, \dots, s_n, x_n, \alpha_n)$$

where for $1 \leq i \leq n$, $s_i \in Q_i$ is the current state of the component A_i , $x_i \in V^*$ is the remaining part of the input word which has not yet been read by A_i , $\alpha_i \in \Delta^*$ is the contents of the i th stack, its first letter being the topmost symbol.

The initial configuration of a parallel communicating pushdown automata system is defined as

$$(q_1, x, Z_1, q_2, x, Z_2, \dots, \dots, q_n, x, Z_n)$$

where q_i is the initial state of the component i , x is the input word, and Z_i is the initial stack symbol of the component i , $1 \leq i \leq n$. It should be noted here that all the components receive the same input word x .

Two variants of transition relations:

First one: $(s_1, x_1, B_1\alpha_1, \dots, s_n, x_n, B_n\alpha_n) \vdash (p_1, y_1, \beta_1, \dots, p_n, y_n, \beta_n)$,
 where $B_i \in \Delta$, $\alpha_i, \beta_i \in \Delta^*$, $1 \leq i \leq n$, iff one of the following two conditions
 holds:

- (i) $K \cap \{B_1, B_2, \dots, B_n\} = \emptyset$ and $x_i = a_i y_i$, $a_i \in V \cup \{\epsilon\}$, $(p_i, \beta'_i) \in f_i(s_i, a_i, B_i)$, $\beta_i = \beta'_i \alpha_i$, $1 \leq i \leq n$,
- (ii) (a) for all i , $1 \leq i \leq n$ such that $B_i = K_{j_i}$ and $B_{j_i} \notin K$, $\beta_i = B_{j_i} \alpha_{j_i} \alpha_i$,
 (b) for all other r , $1 \leq r \leq n$, $\beta_r = B_r \alpha_r$, and
 (c) $y_t = x_t$, $p_t = s_t$, for all t , $1 \leq t \leq n$.

Second one:

$$(s_1, x_1, B_1\alpha_1, \dots, s_n, x_n, B_n\alpha_n) \vdash_r (p_1, y_1, \beta_1, \dots, p_n, y_n, \beta_n),$$

where $B_i \in \Delta$, $\alpha_i, \beta_i \in \Delta^*$, $1 \leq i \leq n$, iff one of the following two conditions holds:

- (i) $K \cap \{B_1, B_2, \dots, B_n\} = \emptyset$ and $x_i = a_i y_i$, $a_i \in V \cup \{\epsilon\}$, $(p_i, \beta'_i) \in f_i(s_i, a_i, B_i)$, $\beta_i = \beta'_i \alpha_i$, $1 \leq i \leq n$,
- (ii) (a) for all $1 \leq i \leq n$ such that $B_i = K_{j_i}$ and $B_{j_i} \notin K$,
 $\beta_i = B_{j_i} \alpha_{j_i} \alpha_i$, and $\beta_{j_i} = Z_{j_i}$,
 (b) for all the other r , $1 \leq r \leq n$, $\beta_r = B_r \alpha_r$, and
 (c) $y_t = x_t$, $p_t = s_t$, for all t , $1 \leq t \leq n$.

The communication between the components has more priority than the usual transitions in individual components. So, whenever a component has a query symbol in the top of its stack it has to be satisfied by the requested component.

- ❑ The stack contents of the sender is retained in the case of relation \vdash , whereas it loses all the symbols in the case of \vdash_r .
- ❑ A parallel communicating pushdown automata system whose computations are based on relation \vdash is said to be *non-returning*; if its computations are based on relation \vdash_r it is said to be *returning*.
- ❑ There are four variants of PCPDA

The language accepted by a parallel communicating pushdown automata system, \mathcal{A} is defined as

$$L(\mathcal{A}) = \{x \in V^* \mid (q_1, x, Z_1, \dots, q_n, x, Z_n) \vdash^* (s_1, \epsilon, \alpha_1, \dots, s_n, \epsilon, \alpha_n), \\ s_i \in F_i, 1 \leq i \leq n\},$$

$$L_r(\mathcal{A}) = \{x \in V^* \mid (q_1, x, Z_1, \dots, q_n, x, Z_n) \vdash_r^* (s_1, \epsilon, \alpha_1, \dots, s_n, \epsilon, \alpha_n), \\ s_i \in F_i, 1 \leq i \leq n\}$$

where \vdash^* and \vdash_r^* denote the reflexive and transitive closure of \vdash and \vdash_r respectively.

- $rcpcpa(n)$ - for returning centralized parallel communicating pushdown automata systems of degree at most n ,
- $rpcpa(n)$ - for returning non-centralized parallel communicating pushdown automata systems of degree at most n ,
- $cpcpa(n)$ - for centralized parallel communicating pushdown automata systems of degree at most n ,
- $pcpa(n)$ - for parallel communicating pushdown automata systems of degree at most n .

If $x(n)$ is a type of automata system, then $X(n)$ is the class of languages accepted by pushdown automata systems of type $x(n)$.

- ❑ $PCPA(2)$ and $RPCPA(3)$ equals RE .
- ❑ $CPCPA(3)$ equals RE .
- ❑ $RCPCPA(k)$ is at least the power of k -head pushdown automata.
- ❑ $RCPCPA(2)$ accepts non- $ETOL$ languages, and hence $RPCPA(2)$ accepts non- $ETOL$ languages.
- ❑ What is the exact power of $RCPCPA/RPCPA(2)$ is it equivalent to RE or properly contained in RE ?

- ❑ Parallel communicating pushdown automata systems with filters
- ❑ Parallel communicating pushdown automata systems with k -symbol communication.
- ❑ Defining automata systems (FSA,PDA) with only synchronizing symbols and with no communication. What will be the power of this model?